

# Cooperative Monitoring for Intelligent Transportation Systems in CVIS

Axel Burkert, Wednesday December 16, 2009

# Agenda

- > Introduction
- > Goals
- > Architecture
- > Main Interfaces
- > Data Distribution
- > Computation of Local Traffic State

## Introduction

### **COOPERATIVE VEHICLE-INFRASTRUCTURE SYSTEMS - CVIS**

- > Create a unified technical solution for V2X communication
- > Create an open application framework

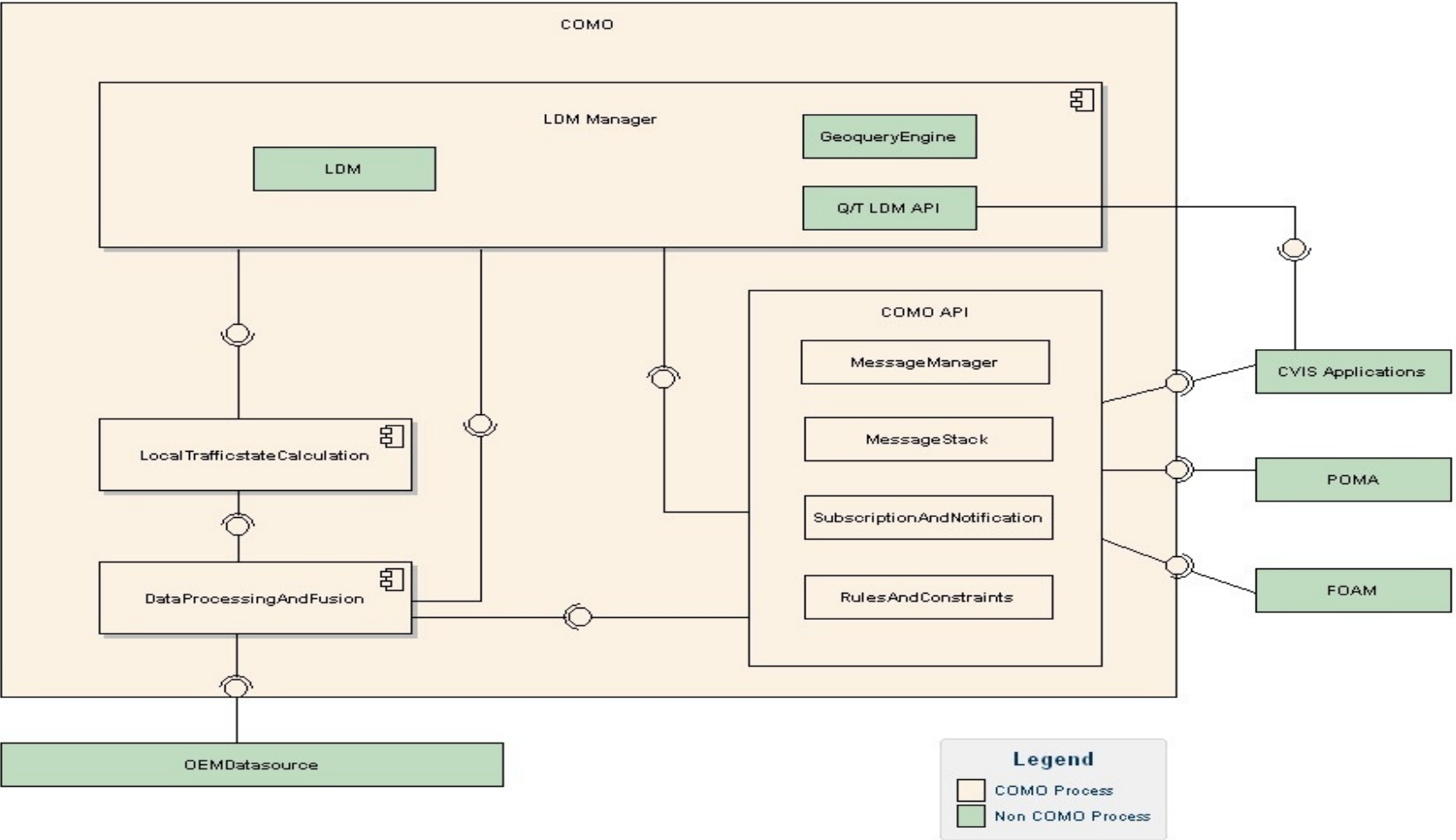
### **Cooperative Monitoring - COMO**

- > Traffic and environmental monitoring as backbone of
  - > enhanced traffic and incident management applications and
  - > traffic related information services
- > Development of specifications and prototypes for
  - > Collection, integration and delivery of extended real-time information

## COMO Goals

- > Central basic service inside the CVIS framework
  - > deployable for operation in a service centre, a road side unit (RSU) and/or the vehicle
- > Development of services and technologies
  - > enabling applications in cooperative systems
- > Elaboration of
  - > traffic data, traffic information and traffic messages
- > Provisioning
  - > in a standardised format to CVIS applications
- > provided as OSGi service

# COMO Architecture



## COMO Interfaces

### Legacy / OEM Gateway

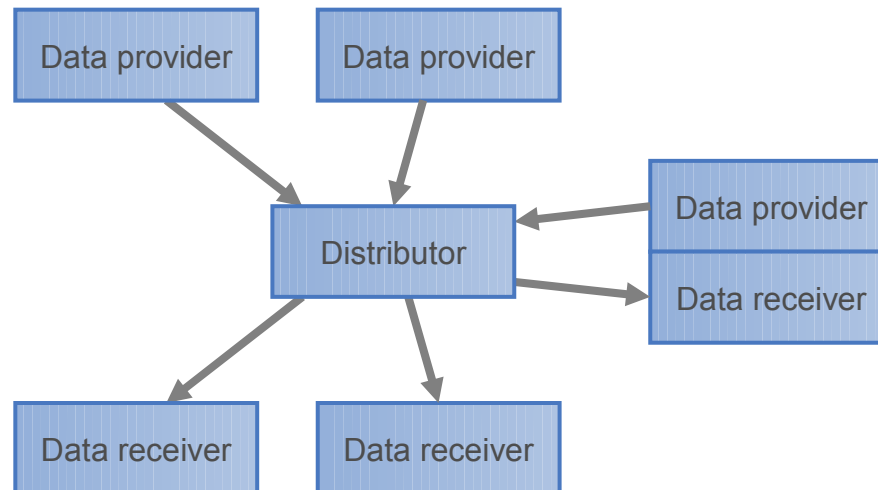
- > Vehicle Platform → CAN Bus / OBD 2
- > Infrastructure Platform → Proprietary
- > Traffic Management Center → DATEX II

### COMO API

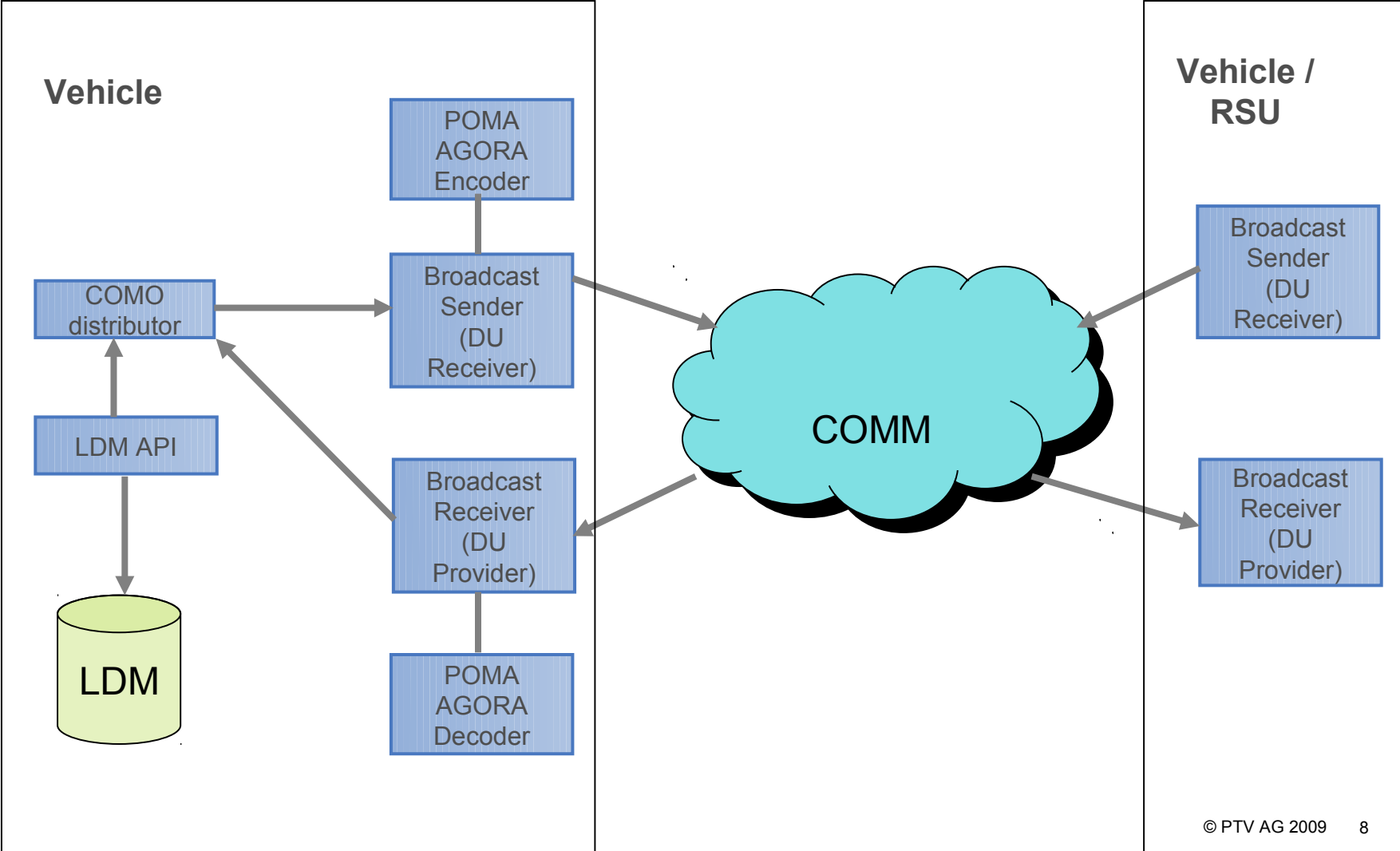
- > Network transparent infrastructure for getting and distributing data
- > Unified interface for traffic related data
- > Fixed set of data to guarantee interoperability between
  - CVIS partner
  - CVIS and Safespot LDM

## COMO Data Distribution

- > Infrastructure for Data Exchange via Mediator
- > Mediator (Distributor) is connected to data sources (Data Provider) and data sinks (Data Receiver)
- > Data Provider --> provide (recent) information
- > Data Receiver --> demand (filtered) information



# COMO Data Distribution II



# COMO Computation of Local Traffic State

## Vehicle Platform

- > e/xFCD generation and data fusion using
  - local sensor data
  - e/xFCD from other vehicles

## Infrastructure Platform

- > Generation of local traffic state using
  - local sensor data
  - vehicle beaconing
  - e/xFCD

## Centre Platform

- > Generation of global traffic state using
  - local traffic state
  - e/xFCD
  - traffic messages

# Erstklassig unterwegs. PTV.

Thank you for your attention

